











#### SN54HC595, SN74HC595

SCLS041I-DECEMBER 1982-REVISED SEPTEMBER 2015

# SNx4HC595 8-Bit Shift Registers With 3-State Output Registers

#### **Features**

- 8-Bit Serial-In, Parallel-Out Shift
- Wide Operating Voltage Range of 2 V to 6 V
- High-Current 3-State Outputs Can Drive Up to 15 LSTTL Loads
- Low Power Consumption: 80-µA (Maximum) I<sub>CC</sub>
- $t_{pd}$  = 13 ns (Typical)
- ±6-mA Output Drive at 5 V
- Low Input Current: 1 µA (Maximum)
- Shift Register Has Direct Clear
- On Products Compliant to MIL-PRF-38535, All Parameters Are Tested Unless Otherwise Noted. On All Other Products, Production Processing Does Not Necessarily Include Testing of All Parameters.

## **Applications**

- **Network Switches**
- Power Infrastructure
- LED Displays
- Servers

## 3 Description

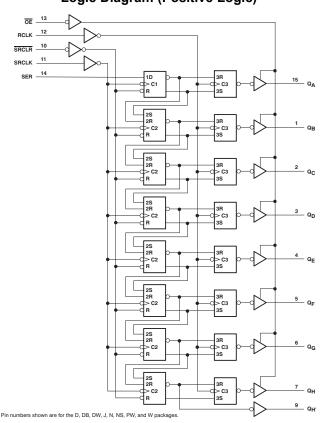
The SNx4HC595 devices contain an 8-bit, serial-in, parallel-out shift register that feeds an 8-bit D-type storage register. The storage register has parallel 3state outputs. Separate clocks are provided for both the shift and storage register. The shift register has a direct overriding clear (SRCLR) input, serial (SER) input, and serial outputs for cascading. When the output-enable (OE) input is high, the outputs are in the high-impedance state.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
SN54HC595	LCCC (20)	8.89 mm x 8.89 mm
3N34HC393	CDIP (16)	21.34 mm x 6.92 mm
	PDIP (16)	19.31 mm × 6.35 mm
	SOIC (16)	9.90 mm x 3.90 mm
SN74HC595	SOIC (16)	10.30 mm x 7.50 mm
	SSOP (16)	6.20 mm x 5.30 mm
	TSSOP (16)	5.00 mm x 4.40 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

## Logic Diagram (Positive Logic)





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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### Changes from Revision H (November 2009) to Revision I

Page

Added Applications section, Device Information table, Pin Configuration and Functions section, ESD Ratings table, Thermal Information table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section
 Deleted Ordering Information table.
 Added Military Disclaimer to Features list.



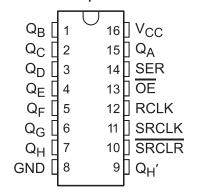
# 5 Device Comparison Table

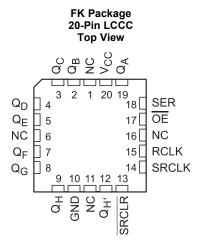
PART NUMBER	PACKAGE	BODY SIZE (NOM)
SN54HC595FK	LCCC (20)	8.89 mm x 8.89 mm
SN54HC595J	CDIP (16)	21.34 mm x 6.92 mm
SN74HC595N	PDIP (16)	19.31 mm × 6.35 mm
SN74HC595D	SOIC (16)	9.90 mm x 3.90 mm
SN74HC595DW	SOIC (16)	10.30 mm x 7.50 mm
SN74HC595DB	SSOP (16)	6.20 mm x 5.30 mm
SN74HC595PW	TSSOP (16)	5.00 mm x 4.40 mm



## 6 Pin Configuration and Functions

D, N, NS, J, DB, or PW Package 16-Pin SOIC, PDIP, SO, CDIP, SSOP, or TSSOP Top View





#### **Pin Functions**

	PIN			
NAME	SOIC, PDIP, SO, CDIP, SSOP, or TSSOP	LCCC	I/O	DESCRIPTION
GND	8	10	_	Ground Pin
ŌĒ	13	17	I	Output Enable
$Q_A$	15	19	0	Q <sub>A</sub> Output
$Q_B$	1	2	0	Q <sub>B</sub> Output
$Q_{C}$	2	3	0	Q <sub>C</sub> Output
$Q_D$	3	4	0	Q <sub>D</sub> Output
$Q_{E}$	4	5	0	Q <sub>E</sub> Output
$Q_{F}$	5	7	0	Q <sub>F</sub> Output
$Q_{G}$	6	8	0	Q <sub>G</sub> Output
$Q_{H}$	7	9	0	Q <sub>H</sub> Output
Q <sub>H</sub> '	9	12	0	Q <sub>H</sub> Output
RCLK	12	14	1	RCLK Input
SER	14	18	1	SER Input
SRCLK	11	14	I	SRCLK Input
SRCLR	10	13	I	SRCLR Input
		1		
NC		16		No Connection
INC		11	_	NO COMBECTION
		16		
V <sub>CC</sub>	_	20	_	Power Pin

Product Folder Links: SN54HC595 SN74HC595

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## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT
$V_{CC}$	Supply voltage		-0.5	7	V
I <sub>IK</sub>	Input clamp current <sup>(2)</sup>	$V_I < 0$ or $V_I > V_{CC}$		±20	mA
lok	Output clamp current (2)	$V_O < 0$ or $V_O > V_{CC}$		±20	mA
Io	Continuous output current	$V_O = 0$ to $V_{CC}$		±35	mA
	Continuous current through V <sub>CC</sub> or GND			±70	mA
T <sub>J</sub>	Junction temperature			150	°C
T <sub>stg</sub>	Storage temperature		-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

			VALUE	UNIT
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	2000	
V <sub>(E</sub>	(SD) Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101, all pins (2)	1000	V

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)(1)

			SN	SN54HC595		SN	5	LIMIT	
			MIN	NOM	MAX	MIN	NOM	MAX	UNIT
$V_{CC}$	Supply voltage		2	5	6	2	5	6	V
		V <sub>CC</sub> = 2 V	1.5			1.5			
$V_{IH}$	High-level input voltage	$V_{CC}$ = 4.5 $V$	3.15			3.15			V
		$V_{CC} = 6 V$	4.2			4.2			
	Low-level input voltage	V <sub>CC</sub> = 2 V			0.5			0.5	
V <sub>IL</sub>		V <sub>CC</sub> = 4.5 V			1.35			1.35	V
		V <sub>CC</sub> = 6 V			1.8			1.8	
VI	Input voltage	·	0		$V_{CC}$	0		$V_{CC}$	V
Vo	Output voltage		0		$V_{CC}$	0		$V_{CC}$	<b>V</b>
		V <sub>CC</sub> = 2 V			1000			1000	
Δt/Δν	Input transition rise or fall time <sup>(2)</sup>	V <sub>CC</sub> = 4.5 V			500			500	ns
		V <sub>CC</sub> = 6 V			400			400	
T <sub>A</sub>	Operating free-air temperature		-55		125	-40		85	°C

All unused inputs of the device must be held at V<sub>CC</sub> or GND to ensure proper device operation. See the TI application report, Implications of Slow or Floating CMOS Inputs, SCBA004.

<sup>(2)</sup> The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

<sup>(2)</sup> If this device is used in the threshold region (from V<sub>IL</sub>max = 0.5 V to V<sub>IH</sub> min = 1.5 V), there is a potential to go into the wrong state from induced grounding, causing double clocking. Operating with the inputs at t<sub>t</sub> = 1000 ns and V<sub>CC</sub> = 2 V does not damage the device; however, functionally, the CLK inputs are not ensured while in the shift, count, or toggle operating modes.



### 7.4 Thermal Information

		SN74AHCT595							
THERMAL METRIC (1)		D (SOIC)	DB (SSOP)	DW (SOIC)	N (PDIP)	NS (SO)	PW (TSSOP)	UNIT	
			16 PINS	16 PINS	16 PINS	16 PINS	16 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance	73	82	57	67	64	108	°C/W	

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

### 7.5 Electrical Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

DADAMETER		ST CONDITIONS	V <sub>cc</sub>	Т	<sub>A</sub> = 25°C		SN54H	C595	SN74H0	C595	UNIT
PARAMETER	"	TEST CONDITIONS		MIN	TYP	MAX	MIN	MAX	MIN	MAX	ONII
			2 V	1.9	1.998		1.9		1.9		
		I <sub>OH</sub> = -20 μA	4.5 V	4.4	4.499		4.4		4.4		
			6 V	5.9	5.999		5.9		5.9		
$V_{OH}$	$V_I = V_{IH}$ or $V_{IL}$	$Q_{H'}$ , $I_{OH} = -4 \text{ mA}$	4.5 V	3.98	4.3		3.7		3.84		V
		$Q_A - Q_H$ , $I_{OH} = -6 \text{ mA}$	4.5 V	3.98	4.3		3.7		3.84		
		$Q_{H'}$ , $I_{OH} = -5.2 \text{ mA}$	6 V	5.48	5.8		5.2		5.34		
		$Q_A - Q_H$ , $I_{OH} = -7.8 \text{ mA}$	- 6 V	5.48	5.8		5.2		5.34		
	$V_I = V_{IH}$ or $V_{IL}$	I <sub>OL</sub> = 20 μA	2 V		0.002	0.1		0.1		0.1	
			4.5 V		0.001	0.1		0.1		0.1	
			6 V		0.001	0.1		0.1		0.1	
$V_{OL}$		$Q_{H'}$ , $I_{OL} = 4 \text{ mA}$	4.5 V		0.17	0.26		0.4		0.33	V
		$Q_A - Q_H$ , $I_{OL} = 6 \text{ mA}$	4.5 V		0.17	0.26		0.4		0.33	
		Q <sub>H</sub> , I <sub>OL</sub> = 5.2 mA	6 V		0.15	0.26		0.4		0.33	
		$Q_A - Q_H$ , $I_{OL} = 7.8 \text{ mA}$	0 V		0.15	0.26		0.4		0.33	
I <sub>I</sub>	$V_I = V_{CC}$ or 0		6 V		±0.1	±100		±1000		±1000	nA
I <sub>OZ</sub>	$V_O = V_{CC}$ or 0, $Q_A - Q_H$		6 V		±0.01	±0.5		±10		±5	μΑ
I <sub>CC</sub>	$V_I = V_{CC}$ or 0, $I_O =$	= 0	6 V			8		160		80	μA
Ci			2 V to 6 V		3	10		10		10	pF



## 7.6 Timing Requirements

over operating free-air temperature range (unless otherwise noted)

			V	T <sub>A</sub> = 25°C		SN54H	C595	SN74H	C595	UNIT
			V <sub>CC</sub>	MIN	MAX	MIN	MAX	MIN	MAX	UNII
			2 V		6		4.2		5	
f <sub>clock</sub>	Clock frequency	,	4.5 V		31		21	·	25	MHz
			6 V		36		25	·	29	
			2 V	80		120		100		
		SRCLK or RCLK high or low	4.5 V	16		24		20		
t <sub>w</sub> Pulse duration		6 V	14		20		17		20	
		2 V	80		120		100		ns	
		SRCLR low	4.5 V	16		24		20		
			6 V	14		20		17		
			2 V	100		150		125		
		SER before SRCLK↑	4.5 V	20		30		25		
			6 V	17		25		21		
		SRCLK↑ before RCLK↑ <sup>(1)</sup>	2 V	75		113		94		
			4.5 V	15		23		19		
	Cat up time		6 V	13		19		16		
t <sub>su</sub>	Set-up time		2 V	50		75		65		ns
		SRCLR low before RCLK↑	4.5 V	10		15		13		
			6 V	9		13		11		
			2 V	50		75		60		
		SRCLR high (inactive) before SRCLK↑	4.5 V	10		15		12		
			6 V	9		13		11		
			2 V	0		0		0		
t <sub>h</sub>	Hold time, SER	after SRCLK↑	4.5 V	0		0		0		ns
				0		0		0		

<sup>(1)</sup> This set-up time allows the storage register to receive stable data from the shift register. The clocks can be tied together, in which case the shift register is one clock pulse ahead of the storage register.



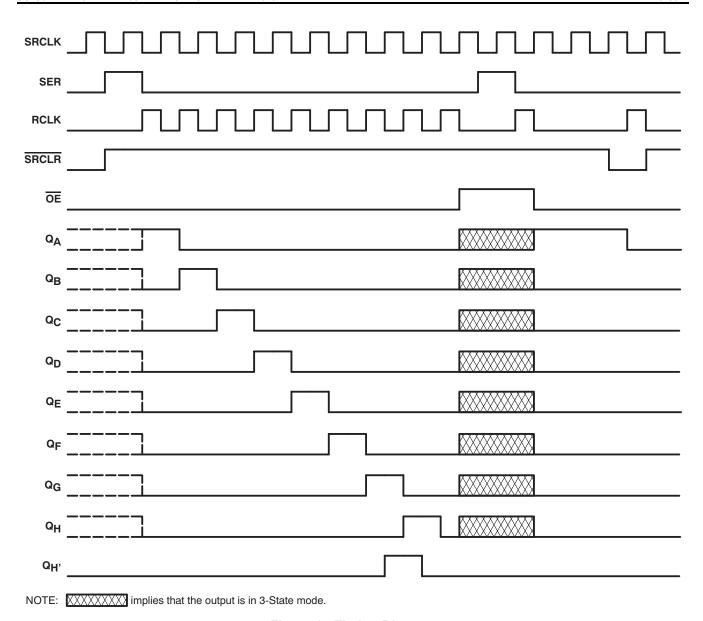


Figure 1. Timing Diagram

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## 7.7 Switching Characteristics

Over recommended operating free-air temperature range.

DADAMETER	FROM	то	LOAD	V	TA	= 25°		SN54H	C595	SN74H	C595	LINUT
PARAMETER	(INPUT)	(OUTPUT)	CAPACITANCE	V <sub>CC</sub>	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNIT
				2 V	6	26		4.2		5		
max			50 pF	4.5 V	31	38		21		25		MHz
				6 V	36	42		25		29		
				2 V		50	160		240		200	
	SRCLK	$Q_{H'}$	50 pF	4.5 V		17	32		48		40	
				6 V		14	27		41		34	
t <sub>pd</sub>				2 V		50	150		225		187	ns
	RCLK	$Q_A - Q_H$	50 pF	4.5 V		17	30		45		37	
				6 V		14	26		38		32	
				2 V		51	175		261		219	
t <sub>PHL</sub>	SRCLR	$Q_{H'}$	50 pF	4.5 V		18	35		52		44	ns
				6 V		15	30		44		37	1
				2 V		40	150		255		187	
en	ŌĒ	$Q_A - Q_H$	50 pF	4.5 V		15	30		45		37	ns
				6 V		13	26		38		32	
				2 V		42	200		300		250	
t <sub>dis</sub>	ŌĒ	$Q_A - Q_H$	50 pF	4.5 V		23	40		60		50	ns
				6 V		20	34		51		43	
				2 V		28	60		90		75	
		$Q_A - Q_H$	50 pF	4.5 V		8	12		18		15	
				6 V		6	10		15		13	
t				2 V		28	75		110		95	ns
		$Q_{H'}$	50 pF	4.5 V		8	15		22		19	
				6 V		6	13		19		16	
				2 V		60	200		300		250	
t <sub>pd</sub>	RCLK	$Q_A - Q_H$	150 pf	4.5 V		22	40		60		50	ns
-				6 V		19	34		51		43	
				2 V		70	200		298		250	
en	ŌĒ	$Q_A - Q_H$	150 pf	4.5 V		23	40		60		50	ns
				6 V		19	34		51		43	
				2 V		45	210		315		265	
t <sub>t</sub>		$Q_A - Q_H$	150 pf	4.5 V		17	42		63		53	ns
-		, , , ,		6 V		13	36		53		45	

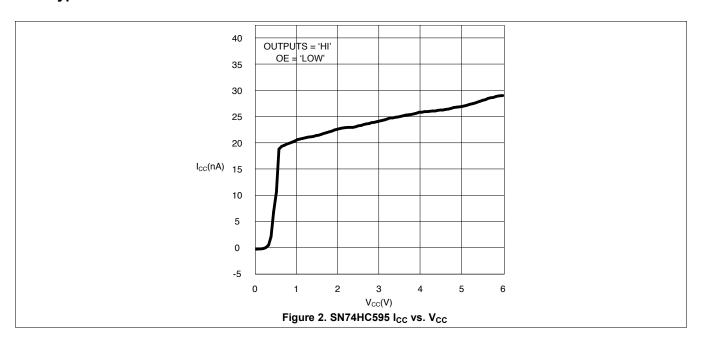
## 7.8 Operating Characteristics

 $T_A = 25^{\circ}C$ 

	PARAMETER	TEST CONDITIONS	TYP	UNIT
$C_{pd}$	Power dissipation capacitance	No load	400	pF

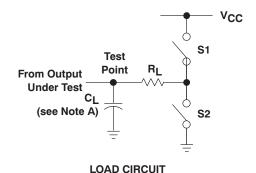


## 7.9 Typical Characteristics

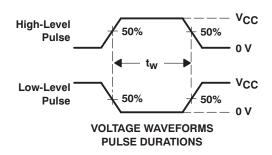


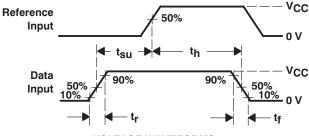


### Parameter Measurement Information

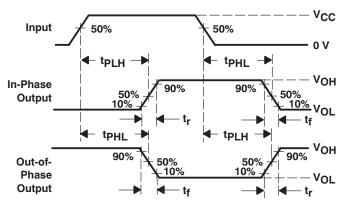


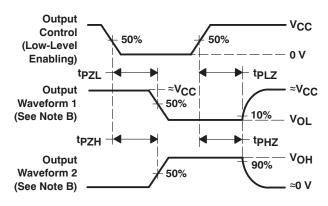
PARAMETER		RL	CL	S1	S2
t <sub>en</sub>	tPZH	<b>1 k</b> Ω	50 pF or 150 pF	Open	Closed
	tPZL			Closed	Open
tdis	tPHZ	<b>1 k</b> Ω	50 pF	Open	Closed
	tPLZ			Closed	Open
t <sub>pd</sub> or t <sub>t</sub>			50 pF or 150 pF	Open	Open





**VOLTAGE WAVEFORMS** SETUP AND HOLD AND INPUT RISE AND FALL TIMES





**VOLTAGE WAVEFORMS** PROPAGATION DELAY AND OUTPUT TRANSITION TIMES

**VOLTAGE WAVEFORMS ENABLE AND DISABLE TIMES FOR 3-STATE OUTPUTS** 

NOTES: A. C<sub>L</sub> includes probe and test-fixture capacitance.

- B. Waveform 1 is for an output with internal conditions such that the output is low, except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high, except when disabled by the output control.
- C. Phase relationships between waveforms were chosen arbitrarily. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  1 MHz,  $Z_O = 50 \Omega$ ,  $t_r = 6 \text{ ns}$ ,  $t_f = 6 \text{ ns}$ .
- D. For clock inputs,  $f_{\text{max}}$  is measured when the input duty cycle is 50%.
- E. The outputs are measured one at a time, with one input transition per measurement.
- F. tpLz and tpHz are the same as tdis.
- G. tpzI and tpzH are the same as ten.
- H. tplH and tpHL are the same as tpd.

Figure 3. Load Circuit and Voltage Waveforms



### 9 Detailed Description

#### 9.1 Overview

The SNx4HC595 is part of the HC family of logic devices intended for CMOS applications. The SNx4HC595 is an 8-bit shift register that feeds an 8-bit D-type storage register.

Both the shift register clock (SRCLK) and storage register clock (RCLK) are positive-edge triggered. If both clocks are connected together, the shift register always is one clock pulse ahead of the storage register.

### 9.2 Functional Block Diagram

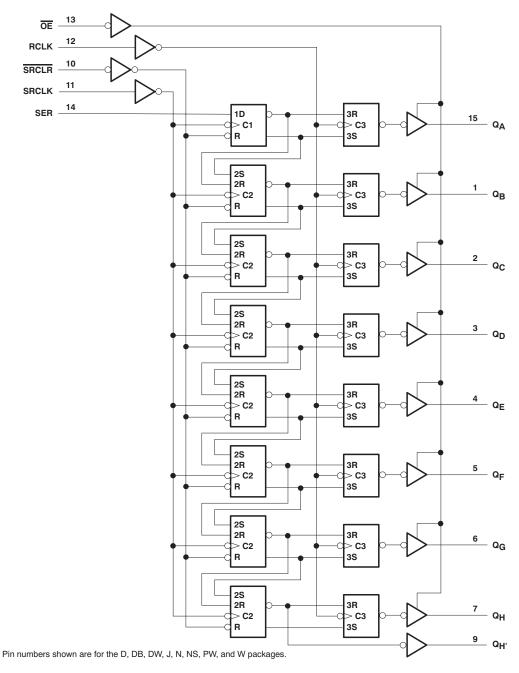


Figure 4. Logic Diagram (Positive Logic)

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### 9.3 Feature Description

The SNx4HC595 devices are 8-bit Serial-In, Parallel-Out Shift Registers. They have a wide operating current of 2 V to 6 V, and the high-current 3-state outputs can drive up to 15 LSTTL Loads. The devices have a low power consumption of 80- $\mu$ A (Maximum) I<sub>CC</sub>. Additionally, the devices have a low input current of 1  $\mu$ A (Maximum) and a ±6-mA Output Drive at 5 V.

### 9.4 Device Functional Modes

Table 1 lists the functional modes of the SNx4HC595 devices.

**Table 1. Function Table** 

INPUTS					EUNCTION	
SER	SRCLK	SRCLR	RCLK	ŌĒ	FUNCTION	
Х	Х	Х	Х	Н	Outputs Q <sub>A</sub> – Q <sub>H</sub> are disabled.	
Х	Х	Х	Х	L	Outputs Q <sub>A</sub> – Q <sub>H</sub> are enabled.	
Х	Х	L	Х	Х	Shift register is cleared.	
L	1	Н	Х	Х	First stage of the shift register goes low. Other stages store the data of previous stage, respectively.	
Н	1	Н	Х	Х	First stage of the shift register goes high. Other stages store the data of previous stage, respectively.	
Х	Х	Х	1	Х	Shift-register data is stored in the storage register.	



## 10 Application and Implementation

### 10.1 Application Information

The SNx4HC595 is a low-drive CMOS device that can be used for a multitude of bus interface type applications where output ringing is a concern. The low drive and slow edge rates will minimize overshoot and undershoot on the outputs.

### 10.2 Typical Application

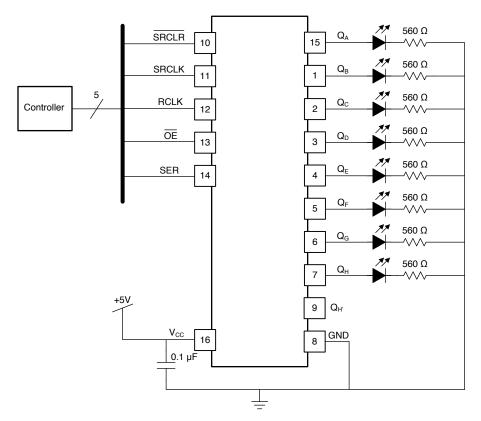


Figure 5. Typical Application Schematic

#### 10.2.1 Design Requirements

This device uses CMOS technology and has balanced output drive. Take care to avoid bus contention because it can drive currents that would exceed maximum limits. The high drive will also create fast edges into light loads so routing and load conditions should be considered to prevent ringing.

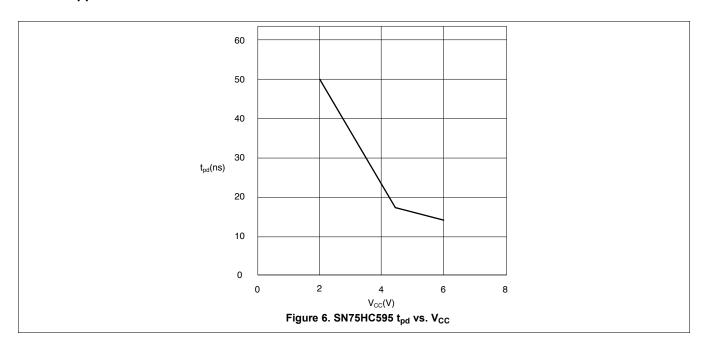
#### 10.2.2 Detailed Design Procedure

- Recommended input conditions
  - Specified high and low levels. See (V<sub>IH</sub> and V<sub>IL</sub>) in the Recommended Operating Conditions table.
  - Specified high and low levels. See (V<sub>IH</sub> and V<sub>IL</sub>) in the *Recommended Operating Conditions* table.
  - Inputs are overvoltage tolerant allowing them to go as high as 5.5 V at any valid  $V_{CC}$
- · Recommend output conditions
  - Load currents should not exceed 35 mA per output and 70 mA total for the part
  - Outputs should not be pulled above V<sub>CC</sub>



## **Typical Application (continued)**

## 10.2.3 Application Curves





## 11 Power Supply Recommendations

The power supply can be any voltage between the minimum and maximum supply voltage rating located in the *Recommended Operating Conditions* table.

Each  $V_{CC}$  pin should have a good bypass capacitor to prevent power disturbance. For devices with a single supply, 0.1  $\mu$ f is recommended; if there are multiple  $V_{CC}$  pins, then 0.01  $\mu$ f or 0.022  $\mu$ f is recommended for each power pin. It is acceptable to parallel multiple bypass caps to reject different frequencies of noise. A 0.1  $\mu$ f and a 1  $\mu$ f are commonly used in parallel. The bypass capacitor should be installed as close to the power pin as possible for best results.

## 12 Layout

### 12.1 Layout Guidelines

When using multiple-bit logic devices, inputs should never float.

In many cases, functions or parts of functions of digital logic devices are unused, for example, when only two inputs of a triple-input AND gate are used or only 3 of the 4 buffer gates are used. Such input pins should not be left unconnected because the undefined voltages at the outside connections result in undefined operational states. Figure 7 specifies the rules that must be observed under all circumstances. All unused inputs of digital logic devices must be connected to a high or low bias to prevent them from floating. The logic level that should be applied to any particular unused input depends on the function of the device. Generally they will be tied to GND or  $V_{CC}$ , whichever makes more sense or is more convenient. It is generally acceptable to float outputs, unless the part is a transceiver. If the transceiver has an output enable pin, it will disable the output section of the part when asserted. This will not disable the input section of the I/Os, so they cannot float when disabled.

### 12.2 Layout Example

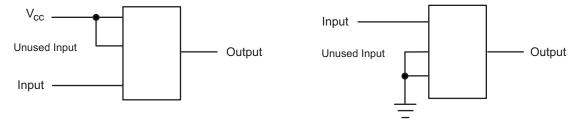


Figure 7. Layout Diagram